

3.7 Variation of Parameter

Consider the differential equation $P(t)y'' + Q(t)y' + R(t) = G(t)$. We've looked at various methods to find the solution:

Method of Reduction of Order

Pros: Straight forward in concept.

Cons: not always easy to implement. Must have one complimentary solution to start with.

Method of Undetermined Coefficients

Pros: Do not need to know the complimentary solution to find the particular solution.

Cons: Only applicable for special cases of $g(t)$ (i.e. polynomial, exponential, sine or cosine)

Method of Variation of Parameter

Pros: can be used when the coefficients are variable (i.e., functions, not just constants)

Cons: the complimentary solutions must be known. Final solution may have to be numerically determined.

Variation of Parameter

If the equation $P(t)y'' + Q(t)y' + R(t) = G(t)$ is divided through by $P(t)$, then the differential equation can be written as

$$y'' + p(t)y' + q(t)y = g(t) \quad (1)$$

and we can assume a solution exists on the interval where p , q , and g are continuous containing t_0 .

Let y_1 and y_2 be solutions to the corresponding homogeneous equation, (e.g., $y_h = C_1 y_1 + C_2 y_2$). Suppose a particular solution is in the form $y_p = u_1(t)y_1(t) + u_2(t)y_2(t)$ for some unknown functions u_1 and u_2 (we are "varying" the parameters C_1 and C_2 to be functions).

To find u_1 and u_2 , first find \dot{y}_p

$$\dot{y}_p = \dot{u}_1 y_1 + u_1 \dot{y}_1 + \dot{u}_2 y_2 + u_2 \dot{y}_2$$

To simplify the algebra later, assume (2) $\dot{u}_1 y_1 + \dot{u}_2 y_2 = 0$. (More about this assumption later.) This means

$$\dot{y}_p = u_1 \dot{y}_1 + u_2 \dot{y}_2$$

and gives us \ddot{y}_p ,

$$\ddot{y}_p = \dot{u}_1 \dot{y}_1 + u_1 \ddot{y}_1 + \dot{u}_2 \dot{y}_2 + u_2 \ddot{y}_2$$

Substituting \ddot{y} , \dot{y} , and y into equation (1) we have

$$\dot{u}_1 \dot{y}_1 + u_1 \ddot{y}_1 + \dot{u}_2 \dot{y}_2 + u_2 \ddot{y}_2 + p u_1 \dot{y}_1 + p u_2 \dot{y}_2 + q u_1 y_1 + q u_2 y_2 = g(t)$$

Rearranging terms we get

$$(\dot{u}_1 \dot{y}_1 + \dot{u}_2 \dot{y}_2) + u_1(\ddot{y}_1 + p \dot{y}_1 + q y_1) + u_2(\ddot{y}_2 + p \dot{y}_2 + q y_2) = g(t)$$

The second and third terms on the left-hand side of the equation are equal to zero (why?), which means $(\dot{u}_1 \dot{y}_1 + \dot{u}_2 \dot{y}_2) = g(t)$, and along with assumption (2) we have the system of equations

$$\begin{aligned} \dot{u}_1 y_1 + \dot{u}_2 y_2 &= 0 \\ \dot{u}_1 \dot{y}_1 + \dot{u}_2 \dot{y}_2 &= g(t) \end{aligned} \quad (2)$$

Solving this system, we get $\dot{u}_1 = \frac{-y_2 \dot{u}_2}{y_1}$, and $\dot{u}_2 = \frac{y_1 g(t)}{y_1 \dot{y}_2 - y_2 \dot{y}_1}$. Substituting \dot{u}_2 back into the previous expression we get

$$\dot{u}_1 = \frac{-y_2 g(t)}{y_1 \dot{y}_2 - y_2 \dot{y}_1} \quad \text{and} \quad \dot{u}_2 = \frac{y_1 g(t)}{y_1 \dot{y}_2 - y_2 \dot{y}_1}$$

Note that the denominators are simply $W(y_1, y_2)$, which gives us

$$u_1 = \int \frac{-y_2 g(t)}{W(y_1, y_2)} dt \quad \text{and} \quad u_2 = \int \frac{y_1 g(t)}{W(y_1, y_2)} dt$$

Therefore, the solution to the differential equation (1) is

$$y = \underbrace{C_1 y_1 + C_2 y_2}_{\text{complimentary}} + \underbrace{u_1 y_1 + u_2 y_2}_{\text{particular}}$$

For those that took Math 204, equation (2) can be written in matrix form

$$\begin{pmatrix} y_1 & y_2 \\ \dot{y}_1 & \dot{y}_2 \end{pmatrix} \begin{pmatrix} \dot{u}_1 \\ \dot{u}_2 \end{pmatrix} = \begin{pmatrix} 0 \\ g(t) \end{pmatrix}$$

Using the inverse matrix we get

$$\begin{pmatrix} \dot{u}_1 \\ \dot{u}_2 \end{pmatrix} = \frac{1}{y_1 \dot{y}_2 - y_2 \dot{y}_1} \begin{pmatrix} \dot{y}_2 & -y_2 \\ -\dot{y}_1 & y_1 \end{pmatrix} \begin{pmatrix} 0 \\ g(t) \end{pmatrix}$$

so,

$$\dot{u}_1 = \frac{-y_2 g(t)}{y_1 \dot{y}_2 - y_2 \dot{y}_1} \quad \text{and} \quad \dot{u}_2 = \frac{y_1 g(t)}{y_1 \dot{y}_2 - y_2 \dot{y}_1}$$

Example 1 Find the general solution to $y'' - 2y' + y = e^t \ln(t)$ for $t > 0$.

Example 2 Observe that $y_1(t) = t$ is a solution of the homogeneous equation $t^2 y'' - t y' + y = 0$, $t > 0$. Use this fact so solve the non-homogeneous IVP $t^2 y'' - t y' + y = t$, $y(1) = 1$, $y'(1) = 4$