

## 6.1-3 Orthogonality

### Inner Product

Let  $\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}$  and  $\mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix}$ . The **inner product** of  $\mathbf{u}$  and  $\mathbf{v}$  is  $(u_1 \ u_2 \ \cdots \ u_n) \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} = u_1 v_1 + u_2 v_2 + \cdots + u_n v_n$ . This is also called the **dot product**  $\mathbf{u} \cdot \mathbf{v}$ .

### Length of a Vector

The length, or **norm**, of a vector is  $\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{v_1^2 + v_2^2 + \cdots + v_n^2}$ . Also note that  $\|\mathbf{v}\|^2 = \mathbf{v} \cdot \mathbf{v}$ .

A vector whose length is 1 is called a **unit vector** and is found by dividing  $\mathbf{v}$  by its norm  $\|\mathbf{v}\|$ :  $\mathbf{u} = \frac{\mathbf{v}}{\|\mathbf{v}\|}$ . The process of creating  $\mathbf{u}$  from  $\mathbf{v}$  is called **normalizing**  $\mathbf{v}$ .

### Distance Between Two Vectors

For vectors  $\mathbf{u}$  and  $\mathbf{v}$  in  $\mathbb{R}^n$ , the **distance between  $\mathbf{u}$  and  $\mathbf{v}$** , written as  $\text{dist}(\mathbf{u}, \mathbf{v})$ , is the length of the vector  $\mathbf{u} - \mathbf{v}$ , that is  $\text{dist}(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|$ .

**Example 1** Find the distance between the vectors  $\mathbf{u} = \begin{pmatrix} 7 \\ 3 \end{pmatrix}$  and  $\mathbf{v} = \begin{pmatrix} 2 \\ 4 \end{pmatrix}$ , and draw a sketch of the three vectors  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{u} - \mathbf{v}$ .

### Orthogonal Vectors

Recall from pre-calculus that another definition of the dot product is  $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos(\theta)$  where  $\theta$  is the angle between  $\mathbf{u}$  and  $\mathbf{v}$ . If the vectors are in  $\mathbb{R}^2$  or  $\mathbb{R}^3$  and are perpendicular, then  $\theta = 90^\circ$ . This means  $\mathbf{u} \cdot \mathbf{v} = 0$ . In general, two vectors  $\mathbf{u}$  and  $\mathbf{v}$  in  $\mathbb{R}^n$  are **orthogonal** if  $\mathbf{u} \cdot \mathbf{v} = 0$ .

**Example 2** Determine which vectors are orthogonal:  $\mathbf{u}_1 = \begin{pmatrix} 2 \\ 3 \\ -4 \end{pmatrix}$ ,  $\mathbf{u}_2 = \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}$ ,  $\mathbf{u}_3 = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$ .

### Orthogonal Complement

Let  $W$  be a subspace of  $\mathbb{R}^n$ . If  $\mathbf{z}$  is orthogonal to every vector in  $W$  then  $\mathbf{z}$  is said to be orthogonal to  $W$ . The set of all vectors  $\mathbf{z}$  that are orthogonal to  $W$  is called the **orthogonal complement** of  $W$  and is denoted by  $W^\perp$ . This leads to two properties:

- (1) A vector  $\mathbf{x}$  is in  $W^\perp$  if and only if  $\mathbf{x}$  is orthogonal to every vector in a set that spans  $W$ .
- (2)  $W^\perp$  is a subspace of  $\mathbb{R}^n$ .

Note: For an  $m \times n$  matrix  $A$   $(\text{Row } A)^\perp = \text{Nul } A$  and  $(\text{Col } A)^\perp = \text{Nul } A^T$ . (Thm 6.1.3)

### Orthogonal Sets

A set of vectors  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_n\}$  is said to be an orthogonal set if each pair of vectors  $\mathbf{u}_i \cdot \mathbf{u}_j = 0$  for all  $i \neq j$ .

**Example 3** Show that  $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  is an orthogonal set, where,  $\mathbf{u}_1 = \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}$ ,  $\mathbf{u}_2 = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$  and  $\mathbf{u}_3 = \begin{pmatrix} -2 \\ -4 \\ 5 \end{pmatrix}$ .

## Orthogonal Basis

An **orthogonal basis** for a subspace  $W$  of  $\mathbb{R}^n$  is a basis for  $W$  that is also an orthogonal set.

### Theorem

Let  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_p\}$  be an orthogonal basis for a subspace  $W$  of  $\mathbb{R}^n$ . For each  $\mathbf{y}$  in  $W$ , the weights in the linear combination  $\mathbf{y} = c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_p \mathbf{u}_p$  are given by  $c_j = \frac{\mathbf{y} \cdot \mathbf{u}_j}{\mathbf{u}_j \cdot \mathbf{u}_j}$ , ( $j = 1, \dots, p$ ).

**Example 4** The set  $S = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  of vectors in example 3 form an orthogonal basis for  $\mathbb{R}^3$ . Express the vector  $\mathbf{y} = \begin{pmatrix} 7 \\ 4 \\ -3 \end{pmatrix}$  in terms of  $S$ .

## Orthonormal Sets; Orthonormal Basis

An orthogonal set of vectors  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_n\}$  each of unit length is called an **orthonormal set**. If  $W$  is a subspace spanned by an orthonormal set, then  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_n\}$  is an orthonormal basis.

**Example 5** Give an example of two well known orthonormal bases.

**Theorem:** An  $m \times n$  matrix  $U$  has orthonormal columns if and only if  $U^T U = I$ .

## Orthogonal Projection

Recall from calculus the quantity  $c = \frac{\mathbf{y} \cdot \mathbf{u}}{\|\mathbf{u}\|}$  is the scalar projection of  $\mathbf{y}$  onto  $\mathbf{u}$ , or the magnitude (amount) of  $\mathbf{y}$  in the direction of  $\mathbf{u}$ . The **orthogonal projection** is the vector  $\hat{\mathbf{y}} = c \mathbf{u}$ , or  $\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u}$ . If  $L$  is the subspace spanned by  $\mathbf{u}$  then  $\hat{\mathbf{y}} = \text{proj}_L \mathbf{y}$ .

**Example 6** Find the closest approximation to  $\mathbf{y} = \langle 3, 1, 5, 1 \rangle$  spanned by  $\mathbf{v}_1 = \langle 3, 1, -1, 1 \rangle$  and  $\mathbf{v}_2 = \langle 1, -1, 1, -1 \rangle$