

4.1 Vector Spaces and Subspaces

Everything we've covered so far can be generalized into more formal concepts called **vector spaces** and **subspaces**. Keep in mind, much of the new idea here is simply *terminology* applied to previous ideas. This will be true for the next several sections.

Definition

A **vector space** is a non-empty set of objects, called vectors, on which are two defined operations called *addition*, and *multiplication by scalars*.

Axioms of a vector space. Let \mathbf{u} , \mathbf{v} , and \mathbf{w} be vectors in a vector space V , and c and d be scalars.

1. The sum of \mathbf{u} and \mathbf{v} , denoted $\mathbf{u} + \mathbf{v}$, is in V .
2. $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$
3. $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
4. There is a zero vector $\mathbf{0}$ in V such that $\mathbf{u} + \mathbf{0} = \mathbf{u}$.
5. For each \mathbf{u} in V , there is a vector $-\mathbf{u}$ in V such that $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$.
6. The scalar multiple of \mathbf{u} by c , denoted by $c\mathbf{u}$, is in V .
7. $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$.
8. $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$.
9. $c(d\mathbf{u}) = (cd)\mathbf{u}$.
10. $1\mathbf{u} = \mathbf{u}$

Examples of Vector Spaces

1. \mathbb{R}^n : points in n -dimensions.
2. Forces used in physics.
3. The set of second order linear differential equations.
4. \mathbb{P}_n : the set of polynomials of degree n .

Subspaces

A subspace is a subset of vectors from a larger vector space. However, \mathbb{R}^2 is not a subspace of \mathbb{R}^3 , since any point on a plane in \mathbb{R}^3 still has three coordinates, and hence in \mathbb{R}^3 .

To show that a **subspace** is a subspace of a larger vector space, only three of the 10 axioms need to be checked (the rest are automatically verified.)

Definition of a Subspace

A **subspace** of a vector space V is a subset H of V that has three properties:

- a. The zero vector of V is in H .
- b. H is closed under addition.
- c. H is closed under scalar multiplication.

Example 1 Is the set consisting of only the zero vector in the vector space V a subspace of V ?

Example 2 Let W be the union of the first and third quadrants in the x - y plane. That is $W = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} : xy \geq 0 \right\}$. If \mathbf{u} is in W and c is any scalar, is $c\mathbf{u}$ in W . Explain. Is it possible to find a \mathbf{u} and \mathbf{v} in W such that $\mathbf{u} + \mathbf{v}$ is not in W ? What does this mean?

Example 3 A plane through the origin is a subspace of \mathbb{R}^3 , but a plane not through the origin is not a subspace of \mathbb{R}^3 . Explain.

Spanning Sets: A Subspace Spanned by a Set

Theorem

If $v_1, v_2 \cdots v_p$ are in a vector space V , then $\text{Span}\{v_1, v_2 \cdots v_p\}$ is a subspace of V .

Example 4 Let H be the set of vectors of the form $(2a, a + 3b, b)$ where a and b are scalars. Show that H is a subspace of \mathbb{R}^3 .