

2.3 Characterizations of Invertible Matrices

Theorem 8 The Invertible Matrix Theorem

Let A be a square $n \times n$ matrix. Then the following statements are equivalent. That is, for a given A , the statements are either all true or all false.

- a. A is an invertible matrix.
- b. A is row equivalent to the $n \times n$ identity matrix.
- c. A has n pivot positions.
- d. The equation $A \mathbf{x} = \mathbf{0}$ has only the trivial solution.
- e. The columns of A form a linearly independent set.
- f. The linear transformation $\mathbf{x} \mapsto A \mathbf{x}$ is one-to-one.
- g. The equation $A \mathbf{x} = \mathbf{b}$ has at least one solution for each \mathbf{b} in \mathbb{R}^n .
- h. The columns of A span \mathbb{R}^n .
- i. The linear transformation $\mathbf{x} \mapsto A \mathbf{x}$ maps \mathbb{R}^n onto \mathbb{R}^n .
- j. There is an $n \times n$ matrix C such that $CA = I$.
- k. There is an $n \times n$ matrix D such that $AD = I$.
- l. A^T is invertible.

Example 1

Demonstrate (or verify) all the properties in Theorem 8 for the matrix $A = \begin{pmatrix} 1 & -1 & 2 \\ 1 & 2 & 0 \\ -2 & 1 & -3 \end{pmatrix}$.

Example 2 Is matrix A invertible? $A = \begin{pmatrix} 1 & 2 & 1 \\ -2 & 2 & 4 \\ 2 & 0 & -2 \end{pmatrix}$ Use Theorem 8.

Invertible Transformations

Recall matrix multiplication is a composition of linear transformations, i.e., $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$. Suppose, however, T is a linear transformation from $\mathbb{R}^n \rightarrow \mathbb{R}^n$. The transformation is said to be invertible if there exists a transformation $S: \mathbb{R}^n \rightarrow \mathbb{R}^n$ such that

1. $S(T(\mathbf{x})) = \mathbf{x}$ for all \mathbf{x} in \mathbb{R}^n , and
2. $T(S(\mathbf{x})) = \mathbf{x}$ for all \mathbf{x} in \mathbb{R}^n .

Example 3 Let the transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be $T(\mathbf{x}) = \begin{pmatrix} 1 & 5 \\ 2 & 11 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$. Find the image of $\mathbf{v} = \begin{pmatrix} -2 \\ 2 \end{pmatrix}$ under T , that is $\mathbf{u} = T(\mathbf{v})$, and find an inverse transformation S , such that $S(\mathbf{u}) = \mathbf{v}$.

Theorem 9

Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation and let A be a transformation matrix for T . Then T is invertible if and only if A is an invertible matrix. In that case, the linear transformation S given by $S(\mathbf{x}) = A^{-1} \mathbf{x}$ is the unique function satisfying equations 1 and 2 above.

III-Conditioned Matrices

It's possible to have an invertible matrix that is "nearly-singular", meaning a small change will make it singular. Such a matrix can give very different results due to round-off errors. The **condition number** for a square matrix can indicate how ill-conditioned a matrix is; the identity matrix has a condition number of 1, and a singular matrix has an infinite condition number.

Example 4 Solve the system of equations: $\begin{cases} 1.51x_1 + 2.27x_2 = b_1 \\ 1.13x_1 + 1.70x_2 = b_2 \end{cases}$ for $\mathbf{b} = \begin{pmatrix} 7.105 \\ 5.319 \end{pmatrix}$, and then with \mathbf{b} rounded to two and one decimal places, using $\mathbf{x} = A^{-1} \mathbf{b}$. Also, use the 2×2 inverse formula to find A^{-1} .