

1.9 The Matrix of a Linear Transformation

In this section we want to try and determine a particular transformation matrix knowing only the transformation on two vectors.

Example 1 Suppose $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, and $\mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$. Let T be a linear transformation such that

$$T(\mathbf{e}_1) = \begin{pmatrix} 2 \\ 4 \\ 1 \end{pmatrix} \text{ and } T(\mathbf{e}_2) = \begin{pmatrix} 4 \\ -5 \\ 1 \end{pmatrix}$$

Find a formula for the image of an arbitrary $\mathbf{x} \in \mathbb{R}^2$. (Note the $[\mathbf{e}_1 \ \mathbf{e}_2]$ is the I_2 identity matrix.)

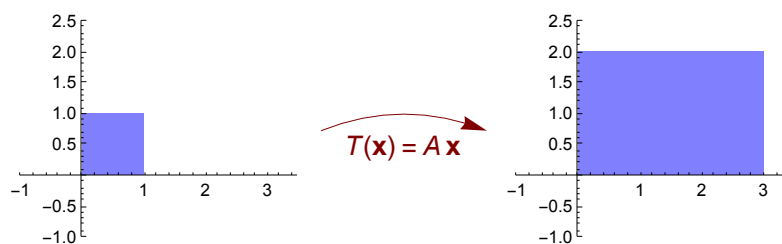
Theorem 10

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Then there exists a unique matrix A such that

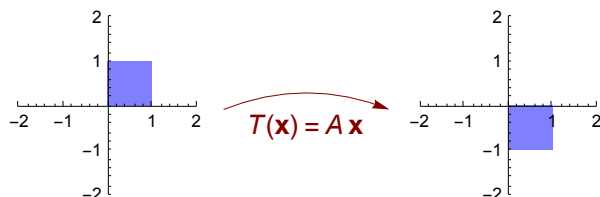
$$T(\mathbf{x}) = A\mathbf{x} \text{ for all } \mathbf{x} \text{ in } \mathbb{R}^n$$

Furthermore $A = [T(\mathbf{e}_1) \ \cdots \ T(\mathbf{e}_n)]$, where \mathbf{e}_j is the j th column of an identity matrix in \mathbb{R}^n . A is call the **standard matrix for the linear transformation T** .

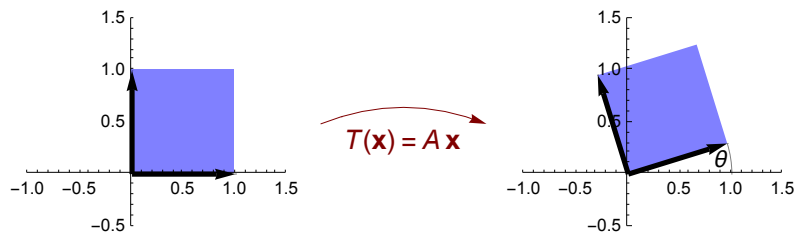
Example 2 Find the matrix that expands any vector \mathbf{x} in \mathbb{R}^2 by 3 horizontally and by 2 vertically. That is, transforms the point $(1, 1)$ to $(3, 2)$, or the vector $\begin{pmatrix} 4 \\ 5 \end{pmatrix}$ to $\begin{pmatrix} 12 \\ 10 \end{pmatrix}$, e.g. $T\left[\begin{pmatrix} 4 \\ 5 \end{pmatrix}\right] = \begin{pmatrix} 12 \\ 10 \end{pmatrix}$. Geometrically, the transformation of the unit square:



Example 3 Find a matrix for the reflection over the horizontal axis.

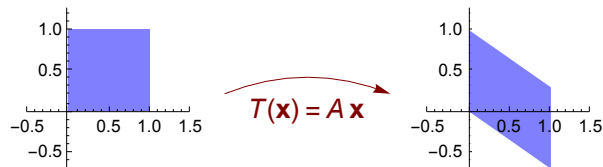


Example 4 Find a rotation matrix for a counterclockwise rotation of θ . Think about where \mathbf{e}_1 and \mathbf{e}_2 are mapped to.



Example 5 Analyze why the transformation $T(\mathbf{x}) = A\mathbf{x}$, where $A = \begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix}$, is a horizontal shear. Again, think about the transformation on \mathbf{e}_1 and \mathbf{e}_2 .

Example 6 Find a matrix that will shear vertically down by a factor of k . Geometrically:



Example 7 Find the transformation matrix that scales the x coordinate of a point in \mathbb{R}^2 by 2, reflects across the y -axis, and rotates 60° .

Theorem 11

Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Then T is one-to-one if and only if the equation $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Theorem 12

Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation and let A be the standard matrix for T . Then:

- T maps \mathbb{R}^n onto \mathbb{R}^m if and only if the columns of A span \mathbb{R}^m ;
 - T is one-to-one if and only if the columns of A are linearly independent.
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